

I What is differential form?

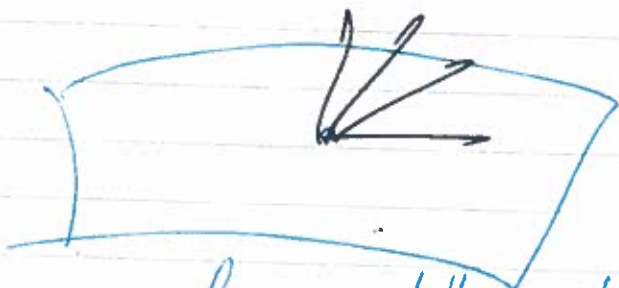
Note: Every time if we integrate "something" over  $k$ -dimensional surface (one dim. curve, two-dim. surf., ...) we in fact integrate differential form (even if we try not to tell this straight forwardly)

II Language of form allows to avoid problems in curve-linear coord.

0-form. Function is function on a point, Diff. 1-form is a function on tangent vectors

$$\omega = \omega(x, \vec{X})$$

tangent vector has to be attached to the point



$T_{x_0} M$  - vectors tangent to  $M$  at the point  $x_0$ .

one-forms at the point  $x_0$  -  $T_{x_0}^* M$  - linear function on tangent vectors

$T_{x_0}^* M$  is vector-space dual to vector space  $T_{x_0} M$ .

Newton law:  $F=ma$  source of confusion,

Too 0-form - just function on points.

Example of 1-form

Let  $f$  be a function

$w(R) = df(x, R) =$  directional derivative of function along vector

$$R^i \frac{\partial f}{\partial x^i} = \partial_R f^*$$

$x_0$   $x(t): \frac{dx^i}{dt} = R^i$

$w = df$  - exact for  $\left. \frac{d}{dt} F(x^i(t)) \right|_{t=0} = R^i \frac{\partial f}{\partial x^i}$

Arbitrary form  $W = \sum w_i(x) dx^i$   
(linear combination of exact forms)

$$w(x, R) = \sum w_i(x) dx^i(R) = \sum R^i w_i(x) = R^i w_i$$

(sometimes  $w_i$  is omitted)

Not every form is exact, but

Exer. if  $w = a dx + b dy$  is 1-form in  $\mathbb{R}^2 \exists$  function  $f$ :  
 $\exists w = df$

\* In some books sometimes they 'define'  
 $df(x, R) = \nabla f \cdot R$   
even number of mistakes

One can integrate 1-form over curve  
(we do not care on coordinates and  
on any additional structure)

$$\int_C \omega = \int_a^b \omega(\vec{v}(t)) dt =$$
$$C: \begin{matrix} x^i = x^i(t) \\ a \leq t \leq b \end{matrix} = \int_a^b \omega_i(x(t)) \frac{dx^i(t)}{dt} dt.$$

Integral DOES NOT depend on coord. on  $X$   
it DOES NOT depend (up to a sign-orientation)  
on parameterisation of the curve) \*

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Sometimes in some books they write

$$\int \vec{A} \cdot d\vec{x} = \int \sum A^i(x) \frac{dx^i}{dt}$$

Vectorfield, scalar product. in fact it is

$$\int g_{ik} A^i(x) dx^k$$

$g_n$

# Two-form

Def. Two-form  $\omega$  is a function depending on two tangent vectors

which is anti symmetric

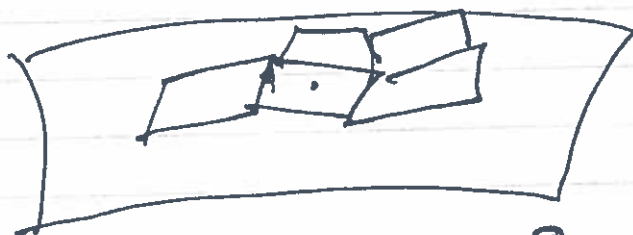
$$\omega = \omega(x, y, \vec{X}, \vec{Y}) =$$

$$\omega(\vec{X}, \vec{Y}) = -\omega(\vec{Y}, \vec{X})$$

(можем даже представить себе + до. определение  
(связь со стар. определением 1-формы)

## Why anti-symmetric. ???

Our aim is to integrate 2-form over surface



$$\int_M \omega \approx \sum \omega(x_i) \text{ Area of } \Pi_{\Delta_i}$$

$$\text{Area of } \Pi_{\Delta_i} = \text{Area of } \Pi(\vec{a}, \vec{b}) = \omega(\vec{a}, \vec{b})$$

for every function on two variables

$$\omega(\vec{a}, \vec{b}) = \omega_S(\vec{a}, \vec{b}) + \omega_{ANT}(\vec{a}, \vec{b})$$

$$\frac{\omega(\vec{a}, \vec{b}) + \omega(\vec{b}, \vec{a})}{2} \quad \frac{\omega(\vec{a}, \vec{b}) - \omega(\vec{b}, \vec{a})}{2}$$

$\omega(\vec{X}, \lambda \vec{X})$  - has to be equal zero!  $\Rightarrow$

hence  $\omega$  - MUST to be anti-symmetric

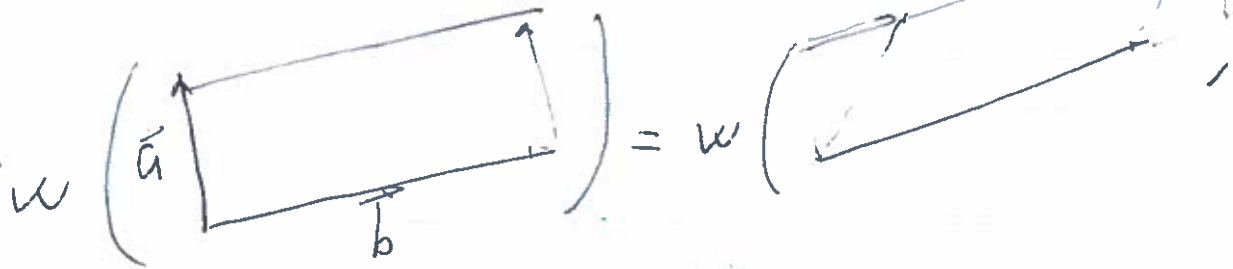
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Now show that this is enough

$$W(\vec{a}, \vec{b}) \sim \text{Area of parallelogram } \Pi_{\vec{a}, \vec{b}}$$



$$W(\vec{a}, \vec{b}) = W(\vec{a}, \vec{b} + \lambda \vec{a})$$



$$W(\vec{a}, \vec{b}) = C \det \begin{pmatrix} a_x & a_y \\ b_x & b_y \end{pmatrix} = C(a_x b_y - a_y b_x)$$

$dx \wedge dy; \underline{\underline{\det}}$

$$dx \wedge dy (\vec{\partial}_x, \vec{\partial}_y) = 1$$

$$W(a \partial_x + b \partial_y, c \partial_x + d \partial_y) =$$

$$= C(ad - bc) W(\partial_x, \partial_y) = ad - bc$$

$$W = C dx \wedge dy$$

wedge product  
 $W = a dx + b y$   
 $d = c dx + d dy$   
 $W \wedge d =$   
 $= (a dx + b dy) \wedge (c dx + d dy)$   
 $= (ad - bc) dx \wedge dy$

$\int dx \wedge dy =$  Area of domain

~~177~~ We can perform integr. in arb. coord. ;

$$\int dx \wedge dy = \int (x_r dr + x_\varphi d\varphi) \wedge (y_r dr + y_\varphi d\varphi) = \int (x_r y_\varphi - x_\varphi y_r) dr \wedge d\varphi =$$

We use notation for vectors dual to

$$\vec{\partial}_x \text{ attached at the point } x_0: \begin{cases} x = x_0 + t \\ y = y_0. \end{cases}$$

$$= \int r dr \wedge d\varphi \quad \begin{cases} x = r \cos \varphi \\ y = r \sin \varphi \end{cases}$$

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Wedge product

$$(dx^1 \wedge dx^2) (\vec{a}, \vec{b}) = -w(\vec{b}, \vec{a}) =$$

$$\vec{a} \wedge \vec{b} = \frac{1}{2} (\vec{a} \otimes \vec{b} - \vec{b} \otimes \vec{a})$$

$w$

$\mathbb{R}$ -form in  
 $u^1, \dots, u^n = \underline{u^i}$

$$w = \sum W_{ij}(u) du^i \wedge du^j$$

$$w(\vec{A}, \vec{B}) = \sum W_{ij}(u) \underline{du^i} \wedge \underline{du^j} (A^m \underline{d_m}, B^n \underline{d_n})$$

$$= \sum W_{ij} A^i B^j$$

One may introduce

$$\vec{A} \wedge \vec{B} = \frac{1}{2} (A \otimes B - B \otimes A)$$

$$(\vec{A} \wedge \vec{B})^{ij} = \frac{1}{2} (A^i B^j - B^i A^j)$$

$$w(\vec{A}, \vec{B}) = w(\vec{A} \wedge \vec{B})$$

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Integral of two-form over surface.

$$\int_M W = M: \begin{cases} u^i = u^i(\xi, \eta) \\ i=1, \dots, n. \end{cases}$$

$$= \int_M W_{ij} du^i \wedge du^j = \int W_{ij} \left( \frac{\partial u^i}{\partial \xi} d\xi + \frac{\partial u^i}{\partial \eta} d\eta \right) \wedge$$

$$\wedge \left( \frac{\partial u^j}{\partial \xi} d\xi + \frac{\partial u^j}{\partial \eta} d\eta \right) =$$

$$= \int W_{ij} \det \begin{pmatrix} u^i_{\xi} & u^i_{\eta} \\ u^j_{\xi} & u^j_{\eta} \end{pmatrix} d\xi d\eta$$

Example.

Flux of vector field through surface

$$\int_M \vec{R} \cdot d\vec{S} = \int_M W_{\vec{R}} =$$

$$W_{\vec{R}}: W_{\vec{R}}(\vec{A}, \vec{B}) = \Omega(\vec{R}, \vec{A}, \vec{B})$$

(in Cartesian coordinates)

$$\int (R^2 dy dz - R^2 dx dz + R^3 dx dy)$$

In <sup>some</sup> ~~many~~ books  $\int \vec{R} \cdot d\vec{S} = \int \vec{R} \cdot d\vec{\sigma} \approx \dots$

← even number of 'mistakes'

## Stokes Theorem.

$$\int_C d\omega = \int \omega$$

$C \qquad \qquad \partial C$

This theorem incorporates many theorems

1.  $\int_a^b f'(x) dx = f(b) - f(a)$

2.  $\oint_{\partial \Omega} \vec{R} \cdot d\vec{S} = \int_{\Omega} \text{div } \vec{R} \, dV \quad (2)$

3.  ~~$\int_M \vec{F} \cdot d\vec{S} =$~~

$M: \partial M = Z$

$$\oint_Z \vec{F} \cdot d\vec{S} = \int_M \text{curl } \vec{F} \cdot d\vec{S}$$

Ex. Prove 2

$$\begin{aligned} \oint \vec{R} \cdot d\vec{S} &= \int_{\partial \Omega} W_{\vec{R}} = \int_{\partial \Omega} [p(x,y,z) (R_x \partial_x + R_y \partial_y + R_z \partial_z)] \\ W_{\vec{R}}(\vec{x}, y/z) &= \Omega(\vec{R}, \vec{x}, y) \\ &= \int_{\partial \Omega} p (R_x dy dz + R_y dz dx + R_z dx dy) = \\ &= \int d [p (R_x dy dz + R_y dz dx + R_z dx dy)] = \end{aligned}$$



$$= \int \left[ \frac{\partial (pR_x)}{\partial x} + \frac{\partial (pR_y)}{\partial y} + \frac{\partial (pR_z)}{\partial z} \right] dx dy dz =$$

$$= \int \frac{1}{\rho} \left( \frac{\partial (pR^i)}{\partial x^i} \right) \Omega$$

$$\text{div } \vec{R} = \frac{1}{\rho} \frac{\partial (pR^i)}{\partial x^i}$$

There are other examples

$$\vec{F} = F_x \partial_x + F_y \partial_y + F_z \partial_z$$

$$\int_Z \vec{F} \cdot d\vec{l} = \int_Z \omega_F = \int (F_x dx + F_y dy + F_z dz) =$$

$$= \int d(F_x dx + F_y dy + F_z dz) =$$

$$= \int \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy + \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) dy dz +$$

$$+ \left( \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) dz dx =$$

$$\int R_2 dx dy + \int R_1 dy dz + \int R_3 dz dx$$

$$= \int_M \vec{R} \cdot d\vec{s}$$

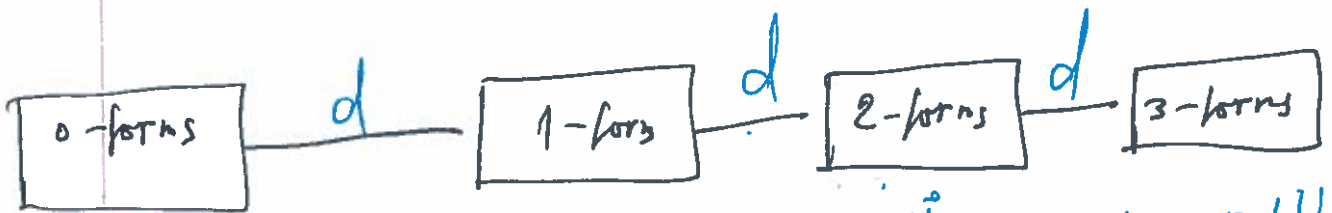
$$\vec{R} = \text{curl } \vec{F}$$

Exercise.

Prove  $\oint_{\partial V} \vec{p} \cdot d\vec{s} = \int_V \rho g$

(Archimedes law).

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Example  
(n=3)



$\text{curl} \circ \text{grad} = 0$   
 $\text{div} \circ \text{curl} = 0$

$\text{curl} \vec{A} = 0 \Rightarrow \vec{A} = \text{grad } U?$   
 $\text{div} \vec{A} = 0 \Rightarrow \vec{A} = \text{curl } U$

0

$d^2 = 0$

$dW = 0 \Rightarrow W = d\delta??$

$\dim \frac{W : dW = 0}{W : W = d\delta} =$   
 $= \text{Betti number}$

And many other things

Homework.

24 X 2018 [Signature]