

### Homework 5a. Solutions.

1 Consider the following curves:

$$C_1: \mathbf{r}(t) \begin{cases} x = t \\ y = 2t^2 - 1, \end{cases} \quad 0 < t < 1, \quad C_2: \mathbf{r}(t) \begin{cases} x = t \\ y = 2t^2 - 1, \end{cases} \quad -1 < t < 1,$$

$$C_3: \mathbf{r}(t) \begin{cases} x = 2t \\ y = 8t^2 - 1, \end{cases} \quad 0 < t < \frac{1}{2}, \quad C_4: \mathbf{r}(t) \begin{cases} x = \cos t \\ y = \cos 2t, \end{cases} \quad 0 < t < \frac{\pi}{2},$$

$$C_5: \mathbf{r}(t) \begin{cases} x = t \\ y = 2t - 1, \end{cases} \quad 0 < t < 1, \quad C_6: \mathbf{r}(t) \begin{cases} x = 1 - t \\ y = 1 - 2t, \end{cases} \quad 0 < t < 1,$$

$$C_7: \mathbf{r}(t) \begin{cases} x = \sin^2 t \\ y = -\cos 2t, \end{cases} \quad 0 < t < \frac{\pi}{2}, \quad C_8: \mathbf{r}(t) \begin{cases} x = t \\ y = \sqrt{1-t^2}, \end{cases} \quad -1 < t < 1,$$

$$C_9: \mathbf{r}(t) \begin{cases} x = \cos t \\ y = \sin t, \end{cases} \quad 0 < t < \pi, \quad C_{10}: \mathbf{r}(t) \begin{cases} x = \cos 2t \\ y = \sin 2t, \end{cases} \quad 0 < t < \frac{\pi}{2},$$

$$C_{11}: \mathbf{r}(t) \begin{cases} x = \cos t \\ y = \sin t, \end{cases} \quad 0 < t < 2\pi, \quad C_{12}: \mathbf{r}(t) \begin{cases} x = a \cos t \\ y = b \sin t, \end{cases} \quad 0 < t < 2\pi \text{ (ellipse),}$$

Draw the images of these curves.

Write down their velocity vectors.

Indicate parameterised curves which have the same image (equivalent curves).

In each equivalence class of parameterised curves indicate curves with same and opposite orientations.

$$C_1: \mathbf{v}(t) = \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} 1 \\ 4t \end{pmatrix}, \quad C_2: \mathbf{v}(t) = \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} 1 \\ 4t \end{pmatrix}, \quad C_3: \mathbf{v}(t) = \begin{pmatrix} 2 \\ 16t \end{pmatrix}, \quad C_4: \mathbf{v}(t) = \begin{pmatrix} -\sin t \\ -2 \sin 2t \end{pmatrix},$$

$$C_5: \mathbf{v}(t) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad C_6: \mathbf{v}(t) = \begin{pmatrix} -1 \\ -2 \end{pmatrix}, \quad C_7: \mathbf{v}(t) = \begin{pmatrix} \sin 2t \\ 2 \sin 2t \end{pmatrix},$$

$$C_8: \mathbf{v}(t) = \begin{pmatrix} 1 \\ \frac{-t}{\sqrt{1-t^2}} \end{pmatrix}, \quad C_9: \mathbf{v}(t) = \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix}, \quad C_{10}: \mathbf{v}(t) = \begin{pmatrix} -2 \sin 2t \\ 2 \cos 2t \end{pmatrix}$$

$$C_{11}: \mathbf{v}(t) = \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix}, \quad C_{12}: \mathbf{v}(t) = \begin{pmatrix} -a \sin t \\ b \cos t \end{pmatrix}$$

Curves  $C_1, C_2, C_3, C_4$

Curves  $C_1, C_3$  and  $C_4$  have the same image: it is piece of parabola  $y = 2x^2 - 1$  between points  $(0, 1)$  and  $(1, 1)$ . Image of the curve  $C_2$  is piece of the same parabola  $y = 2x^2 - 1$  between points  $(-1, 1)$  and  $(1, 1)$ . Image of curve  $C_1$  is a part of the image of the curve  $C_2$ .

Curve  $C_3$  can be obtained from the curve  $C_1$  by reparameterisation  $t(\tau) = 2\tau$ ,  $\mathbf{r}_3(\tau) = \mathbf{r}_1(t(\tau)) = \mathbf{r}_1(2\tau)$ . Respectively  $\mathbf{v}_3(\tau) = t'(\tau)\mathbf{v}_1(t(\tau)) = 2\mathbf{v}_1(2\tau)$ . Curve  $C_4$  can be obtained from the curve  $C_1$  by reparameterisation  $t(\tau) = \cos \tau$ ,  $\mathbf{r}_4(\tau) = \mathbf{r}_1(t(\tau)) = \mathbf{r}_1(\cos \tau)$ . Respectively  $\mathbf{v}_4(\tau) = \begin{pmatrix} -\sin \tau \\ -2 \sin 2\tau \end{pmatrix} = t'(\tau)\mathbf{v}_1(t(\tau)) = -\sin \tau \mathbf{v}_1(\cos \tau) = -\sin \tau \begin{pmatrix} 1 \\ 2 \cos \tau \end{pmatrix}$ .

We see that curves  $C_1, C_3, C_4$  are equivalent. They belong to the same equivalence class of non-parameterised curves. Equivalent curves  $C_1$  and  $C_3$  have the same orientation because diffeomorphism  $t = 2\tau$  has positive derivative. Equivalent curves  $C_1$  and  $C_4$  (and so  $C_3$  and  $C_4$ ) have opposite orientation because diffeomorphism  $t = \cos \tau$  has negative derivative (for  $0 < t < 1$ ).

#### Curves $C_5, C_6, C_7$

Now consider curves  $C_5, C_6, C_7$ . It is easy to see that they all have the same image—segment of the line between point  $(0, -1)$  and  $(1, 1)$ . These three curves belong to the same equivalence class of non-parameterised curves. Curve  $C_6$  can be obtained from the curve  $C_5$  by reparameterisation  $t(\tau) = 1 - \tau$ ,  $\mathbf{r}_6(\tau) = \mathbf{r}_5(t(\tau)) = \mathbf{r}_5(1 - \tau)$ . Respectively  $\mathbf{v}_6(\tau) = t'(\tau)\mathbf{v}_5(t(\tau)) = -\mathbf{v}_5(1 - \tau)$ . (Velocity just changes its direction on opposite.) Curve  $C_7$  can be obtained from the curve  $C_5$  by reparameterisation  $t(\tau) = \sin^2 \tau$ ,  $\mathbf{r}_7(\tau) = \mathbf{r}_5(t(\tau)) = \mathbf{r}_5(\sin^2 \tau)$ . Respectively  $\mathbf{v}_7(\tau) = \begin{pmatrix} \sin 2\tau \\ 2 \sin 2\tau \end{pmatrix} = t'(\tau)\mathbf{v}_5(t(\tau)) = \sin 2\tau \mathbf{v}_5(\sin^2 \tau) = \sin 2\tau \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ .

Equivalent curves  $C_5$  and  $C_7$  have the same orientation because derivative of diffeomorphism  $t = \sin^2 \tau$  is positive (on the interval  $0 < t < 1$ ). Curve  $C_6$  has orientation opposite to the orientation of the curves  $C_5$  and  $C_7$  because derivative of diffeomorphism  $t = 1 - \tau$  is negative. Or in other words when we go to the curve  $C_6$  starting point becomes ending point and vice versa.

#### Curves $C_8, C_9, C_{10}$

Now consider curves  $C_8, C_9, C_{10}$ . It is easy to see that they all have the same image—upper part of the circle  $x^2 + y^2 = 1$ . These three curves belong to the same equivalence class of non-parameterised curves. Curve  $C_9$  can be obtained from the curve  $C_8$  by reparameterisation  $t(\tau) = \cos \tau$ . Then  $\mathbf{r}_9(\tau) = \mathbf{r}_8(t(\tau)) = \mathbf{r}_8(\cos \tau)$ . Respectively  $\mathbf{v}_9(\tau) = t'(\tau)\mathbf{v}_8(t(\tau)) = -\sin \tau \mathbf{v}_8(\cos \tau)$ .

Curve  $C_{10}$  can be obtained from the curve  $C_8$  by reparameterisation  $t(\tau) = 2\tau$ ,  $\mathbf{r}_{10}(\tau) = \mathbf{r}_8(t(\tau)) = \mathbf{r}_8(2\tau)$ . Respectively  $\mathbf{v}_{10}(\tau) = t'(\tau)\mathbf{v}_8(t(\tau)) = 2\tau \mathbf{v}_8(2\tau)$ .

Equivalent curves  $C_8$  and  $C_{10}$  have the same orientation because derivative of diffeomorphism  $t = 2\tau$  is positive. Curve  $C_9$  has orientation opposite to the orientation of the curves  $C_8$  and  $C_{10}$  because derivative of diffeomorphism  $t = \cos \tau$  on the interval  $0 < t < \pi$  is negative.

#### Curves $C_{11}, C_{12}$

Image of the curve  $C_{11}$  is circle  $x^2 + y^2 = 1$ .

Image of the curve  $C_{12}$  is ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .